# I IIISCHaffner 

energy efficiency and reliability



- Reduction of drive output voltage dv/dt
- Restriction of overvoltages on motor cables
- Reduction of motor temperature
- Increase of motor service life
- Improvement of system reliability

Technical specifications

| Nominal operating voltage: | 3x 500/288VAC |
| :---: | :---: |
| Motor frequency: | 0 to 400 Hz (4 to 24A) |
|  | 0 to 200Hz (33 to 66A) |
| Switching frequency: | 2 to 16kHz |
| Rated currents: | 4 to 66A @ $50^{\circ} \mathrm{C}$ |
| Motor cable length: | 80m max. @ 16kHz |
| Voltage drop: | s10V @ 50Hz |
| Typical dv/dt reduction: | Factor 8 to 12 |
| Typical reduction of overvoltages: | $\leq 1000 \mathrm{~V}$ |
| High potential test voltage: | P $\rightarrow$ E 2500VDC for 2 sec |
|  | $\mathrm{P} \rightarrow$ P 1100VDC for 2 sec |
| Protection category: | IP20 |
| Overload capability: | 1.4x rated current for 1 minute, every 15 minutes |
| Temperature range (operation and storage): | $-25^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}(25 / 070 / 21)$ |
| Flammability corresponding to: | UL 94V-2 or better |
| Design corresponding to: | UL 1283, CSA 22.2 No. 8 1986, IEC/EN 60939 |
| MTBF @ $50^{\circ} \mathrm{C} / 400 \mathrm{~V}$ (Mil-HB-217F): | >100,000 hours |

## Features and benefits

- Efficient reduction of high output voltage dv/dt from IGBT motor drives (as per DIN VDE 0530).
- Restriction of overvoltages caused by line reflections on motor cables (as per DIN VDE 0530).
- Protection of motor coil insulation from premature aging and destruction.
- Significant increase of service life of electric motors.
- High reliability and production up time for mission critical applications.
- Less interference propagation towards neighboring equipment or lines.
- Output filter with low impedance, ideal for processes requiring exceptional precision and reproducibility of movements.
- IP20 housing and touch-safe terminal blocks contribute to overall equipment safety.
- Temperature monitoring and internal fan cooling protect the filter from thermal overload.

Design protected by international patent
$\overline{\mathrm{ROHS}}$
2002/95/EC

## Typical block schematic



## Typical applications

- Servo drives
- Close loop vector drives
- Motor drive applications with short to medium motor cable length
- Machinery comprising servo or torque motors
- Robots
- Pick and place machines
- Applications where sine wave filters are not applicable

Filter selection table

| Filter | Rated current <br> @ $50^{\circ} \mathrm{C}$ <br> [A] | Typical motor power rating* <br> [kW] | Typical power loss** | Input/Output connections $\square$ | Weight <br> [kg] |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FN 510-4-29 | 4 | 1.5 | 90 | -29 | 2.1 |
| FN 510-8-29 | 8 | 3.7 | 90 | -29 | 2.1 |
| FN 510-12-29 | 12 | 5.5 | 90 | -29 | 4 |
| FN 510-16-29 | 16 | 7.5 | 90 | -29 | 4.8 |
| FN 510-24-33 | 24 | 11 | 100 | -33 | 7.7 |
| FN 510-33-33 | 33 | 15 | 110 | -33 | 10 |
| FN 510-50-34 | 50 | 22 | 130 | -34 | 21 |
| FN 510-66-34 | 66 | 30 | 150 | -34 | 22 |

* General purpose four-pole (1500r/min) AC induction motor rated 400V/50Hz.
** Power loss at 16 kHz switching frequency/80m motor cable length. Exact value depends upon the motor cable type and length, switching frequency and further stray parameters within the system.


## Typical measurement results

dv/dt without FN 510

dv/dt with FN 510


Overvoltages without FN 510


Overvoltages with FN 510

$\mathrm{dv} / \mathrm{dt}$ reduction: maximum dv/dt at the motor terminals, measured with the motor drive operating at 14 kHz switching frequency, 5 m of shielded cable, motor with $100 \%$ load. Overvoltage limitation: maximum overvoltages at the motor terminals, measured with the motor drive operating at 14 kHz switching frequency, 80 m of shielded cable, motor idling.

## Typical application range at different operating conditions

The power loss in the filter depends mainly on the switching frequency ( fs ) of the motor drive and the length of the motor cable

FN 510 have been designed for an ambient
temperature of $50^{\circ} \mathrm{C}$. Other conditions can, however, occur in practice. In such cases, care must be taken to limit the maximum
cable length and/or the switching frequency of the motor drive, depending on the real ambient temperature conditions.

FN 510 are designed for:

Possible application, e.g.:

## Temperature monitoring function

The temperature monitoring device opens a potential-free contact in the case of filter overtemperature $\left(>120^{\circ} \mathrm{C}\right)$. The maximum
switching capability is $5 \mathrm{~A} / 240 \mathrm{~V}$. The switch can be used, for example, in the input of a CNC controller or as the trip of a circuit
breaker in order to interrupt the mains power supply.

## Mechanical data



Dimensions

|  | 4A | 8A | 12A | 16A | 24A | 33A | 50A | 66A |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | 220 | 220 | 260 | 260 | 350 | 350 | 470 | 470 |
| B | 65 | 65 | 85 | 85 | 110 | 110 | 140 | 140 |
| C | 140 | 140 | 160 | 160 | 190 | 190 | 235 | 235 |
| D | 180 | 180 | 220 | 220 | 310 | 310 | 420 | 420 |
| E | 200 | 200 | 240 | 240 | 330 | 330 | 440 | 440 |
| F | 40 | 40 | 60 | 60 | 70 | 70 | 100 | 100 |
| G | 5.3 | 5.3 | 6.5 | 6.5 | 6.5 | 6.5 | 8.3 | 8.3 |
| H | 1.5 | 1.5 | 1.5 | 1.5 | 2 | 2 | 5 | 5 |
| 1 | 10.9 | 10.9 | 10.9 | 10.9 | 25 | 25 | 39 | 39 |
| J | M4 | M4 | M4 | M4 | M6 | M6 | M8 | M8 |
| K | 10 | 10 | 12.5 | 12.5 | 20 | 20 | 20 | 20 |
| L | 56 | 56 | 65 | 65 | 80 | 80 | 125 | 125 |

All dimensions in mm ; 1 inch $=25.4 \mathrm{~mm}$
Tolerances according: ISO $2768-\mathrm{m} / \mathrm{EN} 22768-\mathrm{m}$

Filter input/output connector cross sections


Please visit www.schaffner.com to find more details on filter connectors.

For additional information please ask for FN 510 installation instructions and the Schaffner application note „Output Filters for Use with Frequency Inverters in Motor Drive Applications".

